

Using the TNT4882 in an MC68340 System

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Introduction

This application note is written for GPIB instrument designers who use the Motorola MC68340 processor. It describes the hardware interface required to create a fully functional GPIB device using the National Instruments TNT4882 GPIB interface chip with the Motorola MC68340.

In this document we show how to create an interface that will meet the following specifications:

- Complete IEEE 488.2 Talker/Listener functionality based on the TNT4882-AQ
- 8 and 16-bit data transfers
- Polled I/O, Interrupt Driven I/O, and Direct Memory Access (DMA)
- 16-bit Single Address DMA transfers between RAM and TNT4882

Note that the terms assert (assertion) and negate (negation) are used to avoid confusion when dealing with a mixture of active low and active high signals. The term assert (assertion) means that a signal is active or true, independent of the level represented by a high or low voltage. The term negate (negation) means that a signal is inactive or false, independent of the level represented by a high or low voltage.

Source files for the test program are included in the *Appendix*. Before you use the hardware test program, make any changes necessary to the header files and recompile the program. We used Microtec Research Software Development Tools, Version 4.2D for DOS and an M68340EVS System.

Hardware Description

The TNT4882 has two different pin configurations – ISA and Generic. This application uses the TNT4882 in Generic pin configuration. Refer to Chapter 5 in the *TNT4882 Programmer Reference Manual* for a Generic pin description. Figure 1 shows the MC68340 and TNT4882 hardware interface diagram. The interface logic can be implemented easily in a Programmable Array Logic (PAL) device such as a 16V8.

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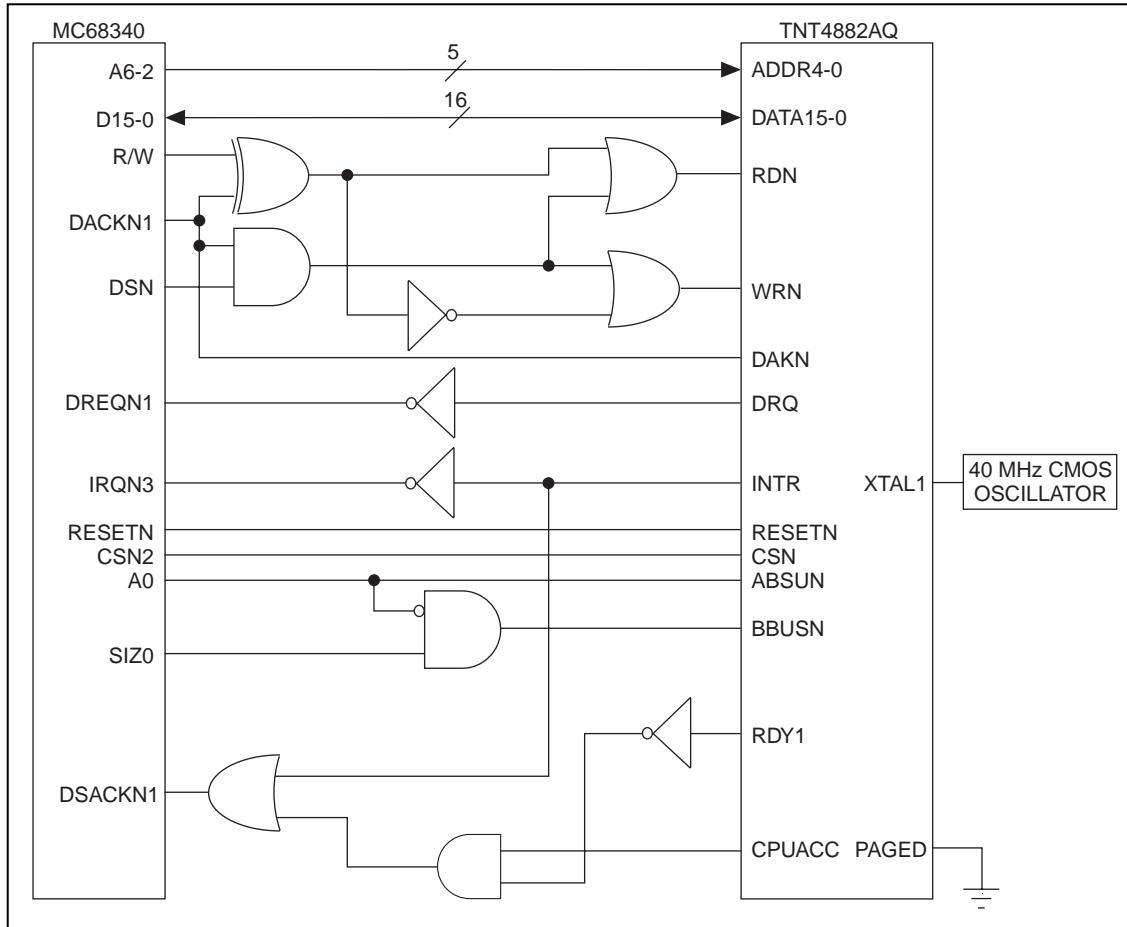


Figure 1. MC68340 and TNT4882 Interface Hardware Diagram

Synchronous Bus Operation

TNT4882 Address Lines

Address lines A6-A2 of MC68340 connect directly to the address lines of TNT4882. Although TNT4882 only requires 32 bytes of address space a total of 256 bytes are assigned. To take advantage of the longword instructions in MC68340, TNT4882 FIFOs must be aligned on a word boundary. For this reason the A6-A2 lines of MC68340 are connected to A4-A0 lines of the TNT4882 chip. Thus every TNT4882 register is assigned to four consecutive address location for a total of 256 bytes.

TNT4882 Data Lines

Since the TNT4882 has built-in transceivers, the data lines connect directly to the CPU without requiring any external pull-up resistors. All TNT4882 registers require 8-bit transfers except FIFO B that allows both 8-bit and 16 bit data transfers. 8-bit I/O accesses can use either data bus. The selection of the data bus is controlled by the ABUSN and BBUSN signals. The only allowed 16-bit accesses are reads and writes to FIFO B. ABUSN and BBUSN must both be asserted during 16-bit I/O accesses.

TNT4882 ABUSN, BBUSN Signals

The TNT4882 has the capability of using either of its data busses for 8-bit I/O accesses. Either Bus A (D15-8) or Bus B (D7-0) can be selected using the ABUSN and BBUSN signals. These two signals can be controlled by using SIZ0 and A0 signals of the processor. Whenever accesses are made to an odd byte address, the processor uses the lower byte of the data bus and whenever accesses are made to an even byte address, the processor uses the upper byte of the data bus. Table 1 shows the ABUSN and BBUSN signals with respect to SIZ0 and A0.

Table 1. ABUSN and BBUSN Signal of TNT4882

MC68340			TNT4882		
Transfer Case	SIZ0	A0	ABUSN	BBUSN	Type of Access
Word Access OR Longword Access	0	0	0	0	16-bit Access
Not Used	0	1	X	X	NONE
Even Byte Access	1	0	0	1	8-bit Access on Upper Byte Lane
Odd Byte Access	1	1	1	0	8-bit Access on Lower Byte Lane

Figures 2 and 3 show the CPU read and write timing diagrams, respectively.

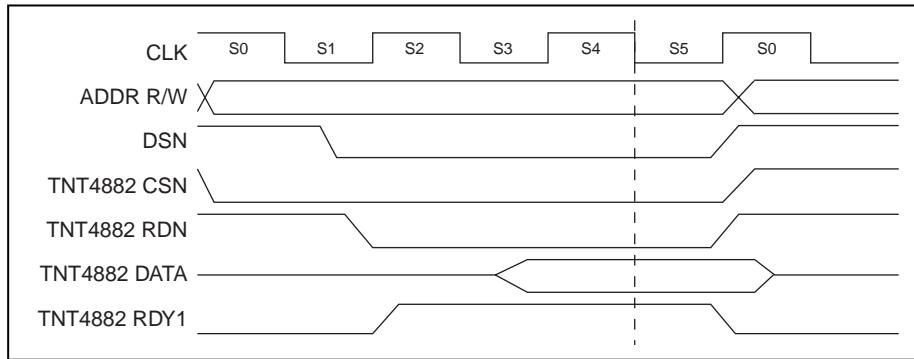


Figure 2. CPU Read Timing Diagram

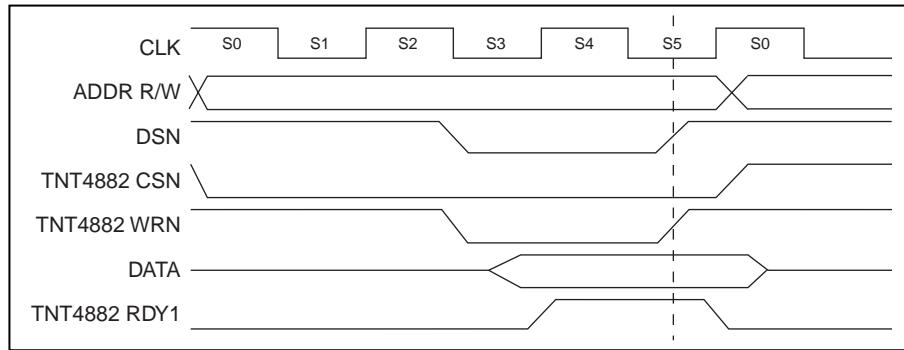


Figure 3. CPU Write Timing Diagram

TNT4882 RDN, WRN Signals

During write accesses, the TNT4882 latches data on the rising edge of WRN. The TNT4882 drives its data buses when RDN is asserted during read accesses. The processor asserts DSN to indicate that an external device should place valid data on the bus during a read access, and that valid data is on the data bus during a write access. The R/W signal indicates the direction of data transfer on the bus. When Direct Memory Access (DMA) is used, DACKN is asserted by the CPU to indicate that a word is being transferred. Since we are implementing single address DMA, DACKN and R/W signals should be used to control RDN and WRN during DMA accesses. Table 2 shows the RDN and WRN signals with respect to R/W, DSN, DACKN.

Table 2. RDN and WRN Signals of TNT4882

MC68340			TNT4882	
R/W	DSN	DACKN	RDN	WRN
0	0	0	0	1
0	0	1	1	0
0	1	0	0	1
0	1	1	1	1
1	0	0	1	0
1	0	1	0	1
1	1	0	1	0
1	1	1	1	1

TNT4882 DMA Signals

The processor has a built-in DMA controller so our system does not require an external DMA controller. The system supports 16-bit Single Address DMA transfers between system memory and the TNT4882 FIFOs. Only one DMA channel is used. Since MC68340 will start DMA when DREQN1 is asserted, the DRQ signal of the TNT4882 must be inverted and then connected to the DREQN1 pin of MC68340. The DACKN signal from the TNT4882 can be connected directly to the DACKN1 pin of MC68340. Figures 4 and 5 show the DMA read and write cycles respectively.

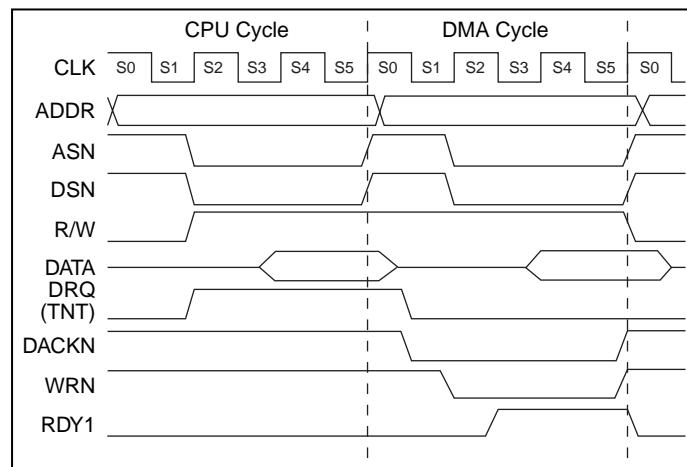


Figure 4. DMA Read (Memory to TNT4882) Timing Diagram

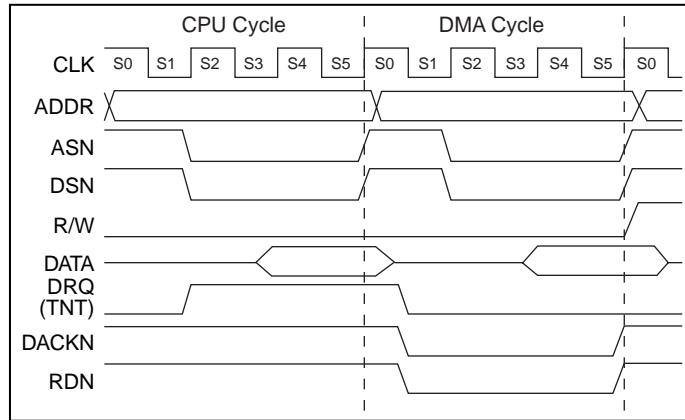


Figure 5. DMA Write (TNT4882 to Memory) Timing Diagram

Asynchronous Bus Operation

Normally, the TNT4882 is used in one chip mode. See Chapter 2 in the *TNT4882 Programmer Reference Manual*. To maintain backwards compatibility, the TNT4882 can be used in two chip mode. In the two chip mode, the TNT4882 duplicates the Turbo488/NAT4882 chipset. In two chip mode the processor can access registers in both the Turbo488 and NAT4882 but all NAT4882 accesses have to pass through the Turbo488, hence they take a little longer time. To accommodate for this feature, one can use the asynchronous timing of MC68340 processor. Asynchronous timing on MC68340 can be controlled by using the DSACKNx pins. The TNT4882 provides two signals namely RDY1 and CPUACC which can allow the user to handle delays in I/O accesses.

The TNT4882 asserts CPUACC to indicate the processor to lengthen the current I/O access. RDY1 indicates that the TNT4882 is ready for the host interface to complete the lengthened cycle if CPUACC is asserted. If CPUACC is not asserted, RDY1 indicates that the current I/O cycle does not need to be lengthened, it does not indicate that the current cycle has finished. Therefore, DSACKN1 should be negated when CPUACC is asserted and RDY1 is negated. See Chapter 5 in the *TNT4882 Programmer Reference Manual*.

Interrupt Acknowledge Bus Operation

The TNT4882 can interrupt the processor by asserting its interrupt signal. The MC68340 will acknowledge the interrupt if its priority is higher than the interrupt mask in the status register. For the above example, interrupt level three has been selected. Since the TNT4882 cannot supply a vector number, it requests an automatically generated vector (autovector). Instead of placing the vector number on the data bus, the autovector register is programmed to generate an autovector. The DSACKNx signals of MC68340 must be negated during the interrupt acknowledge cycle so that the autovector is generated internally. Therefore, DSACKN1 should also be negated when the TNT4882 INTR is asserted. Table 3 shows the DSACKN1 control signals:

Table 3. Signals Used for Controlling Asynchronous I/O

TNT4882			MC68340
RDY1	CPUACC	INTR	DSACKN1
0	0	0	0
0	0	1	1
0	1	0	1
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1

Other CPU Interface Pins¹

Chip Select (CSN)

The CSN pin of the TNT4882 can be connected to one of the available chip select pins of the processor. This allows the chip select to be controlled in software which provides us with some flexibility in moving the TNT4882 anywhere in MC68340 memory map.

Reset (RESETN)

The RESETN pin of the TNT4882 can be connected directly to the RESETN pin of MC68340. Asserting the RESETN signal will reset the TNT4882.

Interrupt Signal (INTR)

MC68340 IRQ lines are active low, so the INTR signal from the TNT4882 must be inverted and then connected to one of the available interrupt lines.

PAGED Pin

When the PAGED pin on the TNT4882 is asserted, the TNT4882 enters the Paged-In state. If Page-In state is true, several registers are mapped to different offsets. In all new applications, PAGED may be connected to GND.

¹ For a detailed description, please refer to Chapter 5 of the *TNT4882 Programmer Reference Manual*.

MODE Pin

The MODE pin determines whether the TNT4882 enters Turbo+7210 mode or Turbo+9914 mode after a hardware reset. For the above interface, MODE was left unconnected so that the TNT4882 enters the Turbo+7210 mode. See the *MODE & SWAPN Pin Recommendations* section of the *TNT4882 Programmer Reference Manual*.

SWAPN Pin

The TNT4882 samples the SWAPN pin during a hardware reset. If SWAPN is asserted during a hardware reset, the SWAP bit is set. For the above interface, SWAPN pin was left unconnected. See the *MODE & SWAPN Pin Recommendations* section of the *TNT4882 Programmer Reference Manual*.

FIFO_RDY Pin

The FIFO_RDY output indicates that the FIFOs are ready for at least 8 word (or byte) transfers. Since we did not have any use for FIFO_RDY, it was left unconnected.

ABUS_OEN and BBUS_OEN

The ABUS_OEN output asserts when the TNT4882 drives Data Bus A during a read access. The BBUS_OEN output asserts when the TNT4882 drives Data Bus B during a read access. Since we did not have any use for the above pins, they were left unconnected.

BURST_RDN

When BURST_RDN is asserted, the TNT4882C drives Data Bus A and Data Bus B with the next word to be read from the FIFOs. BURST_RDN does not remove data from the FIFOs. For the above interface, BURST_RDN was left unconnected.

Key Pins (KEYRSTN, KEYDQ, KEYCLKN)

The key pins are designed to be connected to a Dallas Semiconductor DS1204U Electronic Key. Applications that do not use the key can leave the key pins unconnected.

GPIB Device Status Pins

The TNT4882 has five device status pins: TADCS, LADCS, TRIG, DCAS, and REM. All device status pins are output only so we left them unconnected. For further description of the status pins, refer to the *TNT4882 Programmer Reference Manual*.

GPIB Signal Pins

Connect the GPIB signal pins directly to a GPIB connector.

Oscillator Pins (XTALI, XTALO)

A 40-MHz oscillator is required to drive the clock signal. Connect the oscillator output to the XTALI pin of the TNT4882; leave the XTALO pin unconnected.

Vcc and GND Pins

Supply power to all the Vcc pins and connect the ground signal to all the GND pins.

Software Consideration

Once the hardware interface has been constructed, a few initialization routines need to be performed. Once these initialization sequences are complete, the CPU can be programmed to implement any GPIB device.

System Configuration

System configuration must be performed before the TNT4882 can be used. Configuration of the system requires you to initialize and configure the System Integration Module (SIM), the interrupt registers, and the DMA channel. Once you have configured these modules, the MC68340-TNT4882 interface is fully functional.

System Integration Module Configuration

Configure the appropriate chip select registers in the SIM so that the TNT4882 can be selected. With the above setup, 256 bytes are required. Therefore, CSN2 registers are configured and the TNT4882 is located at \$00FFE800 in MC68340 address space. Table 4 shows the register map of the TNT4882 in MC68340 address space. As you can see, every register in the TNT4882 can be accessed by four different addresses. This setup allows you to use longword accesses from the FIFOs and gives you the choice of using either the upper byte lane or the lower byte lane.

Table 4. Register Map of the TNT4882 in MC68340 Address Space

REGISTER	ADDRESS SPACE
DIR/CDOR	\$FFE800 – \$FFE803
ISR1/IMR1	\$FFE808 – \$FFE80B
ISR2/IMR2	\$FFE810 – \$FFE813
ACCWR	\$FFE814 – \$FFE817
SPSR/SPMR	\$FFE818 – \$FFE81B
INTR	\$FFE81C – \$FFE81F
ADSR/ADMR	\$FFE820 – \$FFE823
CNT2	\$FFE824 – \$FFE827
CPTR/AUXMR	\$FFE828 – \$FFE82B
CNT3	\$FFE82C – \$FFE82F
ADR0/ADR	\$FFE830 – \$FFE833
HSSEL	\$FFE834 – \$FFE837
ADR1/EOSR	\$FFE838 – \$FFE83B
STS1/CFG	\$FFE840 – \$FFE843
DSR/SH_CNT	\$FFE844 – \$FFE847
IMR3	\$FFE848 – \$FFE84B
HIER	\$FFE84C – \$FFE84F
CNT0	\$FFE850 – \$FFE853
MISC	\$FFE854 – \$FFE857
CNT1	\$FFE858 – \$FFE85B
CSR/KEYREG	\$FFE85C – \$FFE85F
FIFO B	\$FFE860 – \$FFE863
FIFO A	\$FFE864 – \$FFE867
ISR3/CCR	\$FFE868 – \$FFE86B
SASR/DCR	\$FFE86C – \$FFE86F
STS2/CMDR	\$FFE870 – \$FFE873
ISR0/IMR0	\$FFE874 – \$FFE877
TIMER	\$FFE878 – \$FFE87B
BSR/BCR	\$FFE87C – \$FFE87F

Interrupt Configuration

Since the above setup requires an autovector, we need to program the autovector register so that the vector number is generated internally when an interrupt is acknowledged. In the above case, we are using interrupt level three, therefore \$08 should be stored in the autovector register.

The vector table should also be modified to point to the new interrupt handler. For interrupt level three, the vector is stored at location \$06C. The value contained at this memory location should be modified to contain the address of the new interrupt handler.

DMA Channel Configuration

In order to use DMA, the DMA channel must be configured for single address, burst mode, and external request generation. On GPIB reads, the TNT4882 will assert its DRQ signal if the FIFOs contain a byte that needs to be transferred to memory. On GPIB writes, the TNT4882 will assert its DRQ signal when the FIFOs are not full.

For every system there is a point where programmed I/O is faster than DMA I/O and vice versa. Programmed I/O is usually faster for small transfer sizes (500 bytes or less). It is recommended that you determine the crossover point and then use it as a switch to decide when to use programmed I/O or DMA.

Device Level Programs

We recommend using the TNT4882 in one-chip mode. The TNT4882 by default powers up in two-chip mode to maintain backwards compatibility. Therefore, it is important to initialize the TNT4882 so that it is in one-chip mode. Follow the steps listed in the *GPIB ESP-488TL Software Reference Manual for TNT4882*. The manual also includes sample routines that can help you write programs for the TNT4882.

Hardware Interface Test

A hardware interface test and library is included with this package. Before you use the hardware test, make any changes if necessary to the header files and re-compile the program. We used Microtec Research Software Development Tools, version 4.2D for DOS and an M68340EVS System. The header files include information such as the base address where the TNT4882 is located. The hardware interface test program tests the interface between MC68340 and TNT4882. It performs three different types of I/O:

- Programmed I/O
- Interrupt Driven I/O
- DMA I/O

To perform the hardware test, download the HARDWARE.ABS file on the MC68340EVS system. The HARDWARE.ABS file is in the HARDWARE directory.

Downloading Procedures

A Widows terminal settings file is also included on the disk. Execute the following steps to download a program:

1. Start Windows.
2. Choose **RUN** from the **FILE** menu.
3. Type **A:\MC68340.TRM** to start the Windows Terminal program.
4. Type **LO** and press **<ENTER>**.
5. Choose **Send Text File** from the **Transfers** menu.
6. Select **HARDWARE.ABS** from **A:\HARDWARE** directory.
7. When download has completed, hit **<ENTER>** twice.

Once the program has been downloaded, use the **RM** command to initialize the MC68340 registers. Set **PC** to \$4000, **USP** to \$8000 and **SSP** to \$10000.

Programmed I/O Test

In Programmed I/O, 5 different tests are conducted that make accesses to FIFOs. These five tests are:

1. 8 Bit Accesses to FIFO A
2. 8 Bit Accesses to FIFO B
3. 16 Bit Accesses to FIFOs
4. 8 Bit Writes and 16 Bit Reads
5. 16 Bit Writes and 8 Bit Reads

Programmed I/O tests 1 and 2 write all possible values (0-255) to both the FIFOs using the upper byte lane and the lower byte lane. Test 3 makes 16-bit accesses to the FIFOs by writing specific values which test the address and data lines (stuck-0,stuck-1,stuck-together). Tests 4 and 5 write the exact same values as in test 3, but 8 bit write and 16 bit read is performed in test 4 while the opposite is performed in test 5. These tests make sure that the FIFOs can be accessed properly and also test the hardware interface such as the address lines, data lines and bus operation signals.

Interrupt Driven I/O Test

By performing the Interrupt Driven I/O we are testing to make sure that the TNT4882 can assert its interrupt line and that it gets acknowledged properly. Before we do any I/O we do a sanity check to make sure that the interrupt handler has been loaded properly. The program reads the contents of memory location \$06C (IRQN3) and compares it with the address of the interrupt handler. If a mismatch occurs, the interrupt handler is not getting loaded properly, or the vector table is being altered which results in the loss of the handler address. Once the handler has been loaded properly, NFF bit of IMR3 is enabled. If FIFOs have room for a byte, an interrupt will occur. After writing to the FIFOs we enable the NEF bit of IMR3. An interrupt will occur if FIFOs contain bytes that need to be transferred to memory.

If the interrupts do not get acknowledged, chances are that the interrupt line is not connected properly. If an unexpected interrupt occurs, then your system may have deleted the address of the new handler from the exception vector table.

DMA I/O Test

DMA I/O tests the functionality of the DMA Channel and its associated interface logic. For example, when a DMA read is performed, data is transferred from memory (read from memory) to the TNT4882. If data transfers do not take place, chances are that WRN signal is not asserting during the DMA read cycle. Similarly, during a DMA write cycle, RDN should be asserted because data is transferred from FIFOs to memory.

In the DMA I/O test routine, the channel is initialized by clearing the status register and loading the byte transfer value in the byte counter register. The channel is then started, and DMA takes place when the DREQN1 pin of MC68340 goes low. DMA read takes place first where values are written to the FIFOs. DMA write takes place later where values are read back from the FIFOs.

MC340BUG Library

A Library is also included with the software package. The MC340BUG library provides basic I/O functions that use the M340BUG debug system calls. System calls use Trap #15 for I/O functions. Therefore Trap #15 is not available for user programs. The library was created using Microtec's Librarian. This library package is only useful if you are developing programs using Microtec Research Software Development Tools.

Description of Library Functions

ERASLN()

Purpose	Erase the line at the present cursor position
Parameters	NONE
Return Type	void
Example	ERASLN();

NEWLN()

Purpose	Skip a line
Parameters	NONE
Return Type	void
Example	NEWLN();

getchar()

Purpose	Read a character from the input port
Parameters	NONE
Return Type	char
Example	c = getchar();

putchar()

Purpose	Write a character to the output port
Parameters	character to be written
Return Type	void
Example	putchar('a'); putchar(chr) where chr = 'z';

puts()

Purpose	Output a line to the output port
Parameters	string to be written
Return Type	void
Example	puts("hello"); puts(str) where str = "how are you?";

PrintHex()

Purpose	Output a number in hexadecimal form
Parameters	unsigned short int (0 - 65535)
Return Type	void
Example	PrintHex(321); PrintHex(num) where num = 3245;

RET340BUG()

Purpose	Restore control to 340Bug from the target program
Parameters	NONE
Return Type	void
Example	RET340BUG();

References

1. *MC68340 Integrated Processor with DMA User's Manual*, Motorola Inc., 1992.
2. *TNT4882 Programmer Reference Manual*, National Instruments, 1994.
3. *ESP-488TL Software Reference Manual for TNT4882*, National Instruments, 1994.
4. *M68340BUG Debug Monitor and Assembler User's Manual*, Motorola Inc., 1991.
5. *M68340EVS Evaluation System User's Manual*, Motorola Inc., 1991.

Appendix

Source File	Description	Page
Register.H	TNT4882 Register Declarations	12
MC68340.H	MC68340 Register Declarations	17
MC340BUG.H	340 Bug Debug Monitor Functions	19
HARDWARE.H	Test Program Header File	19
HARDWARE.C	Test Program Source Code	20
TNT4882.H	TNT4882 Test Function Declarations	26
TNT4882.C	TNT4882 Test Functions	26

Register.H

```
#ifndef __REGISTER_H
#define __REGISTER_H

#define BASE      0x00FFE800

#define DIR      *(unsigned char *) (BASE + 0x00)

#define CDOR     *(unsigned char *) (BASE + 0x00)

#define IMR0      *(unsigned char *) (BASE + 0x75)
#define E_BTO      0x10
#define E_GLINT    0x80

#define ISR0      *(unsigned char *) (BASE + 0x75)
#define E_SYNC     0x01
#define E_TO       0x02
#define E_ATNI    0x04
#define E_IFCI     0x08
#define E_EOS      0x10
#define E_NL       0x20
#define E_STBO    0x40
#define E_CDBA    0x80

#define IMR1      *(unsigned char *) (BASE + 0x08)

#define ISR1      *(unsigned char *) (BASE + 0x08)
#define E_DI       0x01
#define E_DO       0x02
#define E_ERR      0x04
#define E_DEC      0x08
#define E_END      0x10
#define E_DET      0x20
#define E_APT      0x40
#define E_isrCPT  0x80

#define IMR2      *(unsigned char *) (BASE + 0x10)
#define E_DMAI    0x10
#define E_DMAO    0x20

#define ISR2      *(unsigned char *) (BASE + 0x10)
#define E_ADSC    0x01
#define E_REMC    0x02
#define E_LOKC    0x04
#define E_Rem     0x10
#define E_LOK     0x20
#define E_INT     0x80

#define IMR3      *(unsigned char *) (BASE + 0x48)
#define E_DONE    0x01
#define E_TLCINT  0x02
#define E_NEF     0x04
#define E_NFF     0x08
#define E_STOP    0x10
#define E_SRQ     0x20
#define E_INTSR   0x40
#define ISR3      *(unsigned char *) (BASE + 0x68)
#define E_X       0x80
#define ACCWR    *(unsigned char *) (BASE + 0x15)

#define SPSR      *(unsigned char *) (BASE + 0x18)
#define B_S1      (SPSR & 0x01)
#define B_S2      (SPSR & 0x02)
```

```

#define B_S3      (SPSR & 0x04)
#define B_S4      (SPSR & 0x08)
#define B_S5      (SPSR & 0x10)
#define B_S6      (SPSR & 0x20)
#define B_PEND    (SPSR & 0x40)
#define B_S8      (SPSR & 0x80)

#define SPMR      *(unsigned char *) (BASE + 0x18)
#define E_S1      0x01
#define E_S2      0x02
#define E_S3      0x04
#define E_S4      0x08
#define E_S5      0x10
#define E_S6      0x20
#define E_PEND    0x40
#define E_S8      0x80

#define INTR      *(unsigned char *) (BASE + 0x1D)

#define ADSR      *(unsigned char *) (BASE + 0x20)
#define B_MJMN    (ADSR & 0x01)
#define B_TA      (ADSR & 0x02)
#define B_LA      (ADSR & 0x04)
#define B_TPAS    (ADSR & 0x08)
#define B_LPAS    (ADSR & 0x10)
#define B_SPMS    (ADSR & 0x20)
#define B_ATN1    (ADSR & 0x40)
#define B_CIC     (ADSR & 0x80)

#define ADMR      *(unsigned char *) (BASE + 0x20)
#define NoAddr   0x30
#define NormDual 0x31
#define ExSingle 0x32
#define ExDual   0x33
#define ListOnly 0x70
#define TalkOnly 0xB0

#define CPTR      *(unsigned char *) (BASE + 0x28)

#define AUXMR    *(unsigned char *) (BASE + 0x28)

#define PON      0x00
#define ClrIST  0x01
#define RstChip 0x02
#define RHDF    0x03
#define TRIG    0x04
#define ClrRTL  0x05
#define SEOI    0x06
#define NonValid 0x07
#define RQC     0x08
#define SetIST  0x09
#define RLC     0x0A
#define LUT     0x0B
#define LUL     0x0C
#define SetRTL  0x0D
#define NBAF    0x0E
#define Valid   0x0F
#define GTS     0x10
#define TCA     0x11
#define TCS     0x12
#define LTN     0x13
#define DisRSC  0x14
#define Turbo9914 0x15
#define ClrIFC  0x16

```

```

#define ClrREN      0x17
#define REQT        0x18
#define REQF        0x19
#define TCSE        0x1A
#define LTNnCont   0x1B
#define LUN         0x1C
#define RPPL        0x1D
#define SetIFC      0x1E
#define SetREN      0x1F
#define PageIn      0x50
#define HLDI        0x51
#define ClrDET      0x54
#define ClrEND      0x55
#define ClrDEC      0x56
#define ClrERR      0x57
#define ClrSRQI     0x58
#define ClrLOKC     0x59
#define ClrREMC     0x5A
#define ClrADSC     0x5B
#define ClrIFCI     0x5C
#define ClrATNI     0x5D
#define ClrSYNC      0x5E
#define SetSYNC     0x5F

#define PPR         0x60
#define P(value)    (PPR | value)
#define E_S         (PPR | 0x08)
#define E_U         (PPR | 0x10)

#define AUXRA       0x80
#define E_HLDA      (AUXRA | 0x01)
#define E_HLDE      (AUXRA | 0x02)
#define E_REOS      (AUXRA | 0x04)
#define E_XEOS      (AUXRA | 0x08)
#define E_BIN       (AUXRA | 0x10)

#define AUXRB       0xA0
#define E_auxCPT   (AUXRB | 0x01)
#define E_SPEOI     (AUXRB | 0x02)
#define E_TRI       (AUXRB | 0x04)
#define E_ISS       (AUXRB | 0x80)

#define AUXRE       0xC0
#define E_DHDC      (AUXRE | 0x01)
#define E_DHDT      (AUXRE | 0x02)
#define E_DHADC     (AUXRE | 0x04)
#define E_DHADT     (AUXRE | 0x08)

#define AUXRF       0xD0
#define E_DHALL     (AUXRF | 0x01)
#define E_DHUNTL   (AUXRF | 0x02)
#define E_DHALA     (AUXRF | 0x04)
#define E_DHATA     (AUXRF | 0x08)

#define AUXRG       0x40
#define E_CHE8      (AUXRG | 0x01)
#define E_DISTCT   (AUXRG | 0x02)
#define E_RPP2      (AUXRG | 0x04)
#define E_NTNL      (AUXRG | 0x08)

#define AUXRI       0xE0
#define E_SISB      (AUXRI | 0x01)
#define E_PP2       (AUXRI | 0x04)
#define E_USTD      (AUXRI | 0x08)

```

```

#define AUXRJ      0xF0
#define TM(value)  (AUXRJ | value)

#define CNT3      *(unsigned char *) (BASE + 0x2D)
#define CNT2      *(unsigned char *) (BASE + 0x25)
#define CNT1      *(unsigned char *) (BASE + 0x58)
#define CNT0      *(unsigned char *) (BASE + 0x50)

#define ADR0      *(unsigned char *) (BASE + 0x30)
#define F_ADR0    (ADR0 & 0x1F)
#define B_DL0     (ADR0 & 0x20)
#define B_DT0     (ADR0 & 0x40)

#define ADR      *(unsigned char *) (BASE + 0x30)
#define ADDR(val) (ADR | val)
#define E_DL     0x20
#define E_DT     0x40
#define E_ARS    0x80

#define HSSEL     *(unsigned char *) (BASE + 0x35)
#define E_ONEC   0x01
#define E_NODMA  0x10
#define E_GO2SIDS 0x20

#define ADR1      *(unsigned char *) (BASE + 0x38)
#define F_ADR1    (ADR1 & 0x1F)
#define B_DL1     (ADR1 & 0x20)
#define B_DT1     (ADR1 & 0x40)
#define B_EOII1   (ADR1 & 0x80)

#define EOSR     *(unsigned char *) (BASE + 0x38)

#define STS1      *(unsigned char *) (BASE + 0x40)
#define B_GSYNC   (STS1 & 0x01)
#define B_HALT    (STS1 & 0x02)
#define B_DAV     (STS1 & 0x04)
#define B_stsSTOP (STS1 & 0x08)
#define B_DRQ     (STS1 & 0x10)
#define B_IN      (STS1 & 0x20)
#define B_SC      (STS1 & 0x40)
#define B_stsDONE (STS1 & 0x80)

#define CFG       *(unsigned char *) (BASE + 0x40)
#define E_168N   0x01
#define E_TIM    0x02
#define E_TMOE   0x04
#define E_CCEN   0x08
#define E_ABN    0x10
#define E_IN     0x20
#define E_TLCHLTE 0x40
#define E_COMMAND 0x80

#define DSR      *(unsigned char *) (BASE + 0x45)
#define SHCNT    *(unsigned char *) (BASE + 0x45)

#define pt1      0x00
#define E_PT1    (pt1 | 0x20)
#define PT1(value) (pt1 | value)
#define t17      0x40
#define T17(value) (t17 | value)

#define t12      0x80
#define T12(value) (t12 | value)

```

```

#define t13      0xC0
#define T13(value) (t13 | value)

#define HIER      *(unsigned char *) (BASE + 0x4D)
#define E_PMTwEOS 0x01
#define E_NTSETUP 0x10
#define E_DGB     0x40
#define E_DGA     0x80

#define MISC      *(unsigned char *) (BASE + 0x55)
#define E_NOTS    0x01
#define E_NOAS    0x02
#define E_WRAP    0x04
#define E_SLOW    0x08
#define E_HSE     0x10

#define CSR       *(unsigned char *) (BASE + 0x5D)

#define KEYREG    *(unsigned char *) (BASE + 0x5D)

#define FIFO      *(unsigned short int *) (BASE + 0x60)
#define FIFOB     *(unsigned char *) (BASE + 0x60)
#define FIFOA     *(unsigned char *) (BASE + 0x65)
#define CCR       *(unsigned char *) (BASE + 0x68)

#define SASR      *(unsigned char *) (BASE + 0x6D)
#define B_SH1B    (SASR & 0x01)
#define B_SH1A    (SASR & 0x02)
#define B_ACRDY   (SASR & 0x04)
#define B_ADHS    (SASR & 0x08)
#define B_ANHS2   (SASR & 0x10)
#define B_ANHS1   (SASR & 0x20)
#define B_AEHS    (SASR & 0x40)
#define B_NBA1    (SASR & 0x80)

#define DCR       *(unsigned char *) (BASE + 0x6D)

#define STS2      *(unsigned char *) (BASE + 0x70)
#define B_BEFN    (STS2 & 0x01)
#define B_BFFN    (STS2 & 0x02)
#define B_AEFN    (STS2 & 0x04)
#define B_AFFN    (STS2 & 0x08)
#define B_168N    (STS2 & 0x40)

#define CMDR     *(unsigned char *) (BASE + 0x70)
#define DiSysCon 0x02
#define EnSysCon 0x03
#define GO        0x04
#define STOP      0x08
#define RstFIFO   0x10
#define SftRst    0x22

#define TIMER     *(unsigned char *) (BASE + 0x78)

#define BSR       *(unsigned char *) (BASE + 0x7D)
#define B_REN     (BSR & 0x01)
#define B_IFC     (BSR & 0x02)
#define B_bsrSRQ (BSR & 0x04)
#define B_EOI     (BSR & 0x08)
#define B_NRFD   (BSR & 0x10)
#define B_NDAC   (BSR & 0x20)

```

```
#define B_bsrDAV (BSR & 0x40)
#define B_ATN (BSR & 0x80)

#define BCR *(unsigned char *) (BASE + 0x7D)
#define E_REN 0x01
#define E_IFC 0x02
#define E_bcrSRQ 0x04
#define E_EOI 0x08
#define E_NRFD 0x10
#define E_NDAC 0x20
#define E_bcrDAV 0x40
#define E_ATN 0x80

#endif
```

MC68340.H

```
#ifndef __MC68340_H
#define __MC68340_H

#define MCBASE 0xFFFFF000

/******System Integration Module (SIM)*****/
#define AVR     *(unsigned char *) (MCBASE + 0x006)
#define RSR     *(unsigned char *) (MCBASE + 0x007)
#define PORTA   *(unsigned char *) (MCBASE + 0x011)
#define DDRA    *(unsigned char *) (MCBASE + 0x013)
#define PPARA1  *(unsigned char *) (MCBASE + 0x015)
#define PPARA2  *(unsigned char *) (MCBASE + 0x017)
#define PORTB   *(unsigned char *) (MCBASE + 0x019)
#define PORTB1  *(unsigned char *) (MCBASE + 0x01B)
#define DDRB    *(unsigned char *) (MCBASE + 0x01D)
#define PPARB   *(unsigned char *) (MCBASE + 0x01F)
#define SWIV    *(unsigned char *) (MCBASE + 0x020)
#define SYPCR   *(unsigned char *) (MCBASE + 0x021)
#define SWSR    *(unsigned char *) (MCBASE + 0x027)
#define SIMMCR  *(unsigned short int *) (MCBASE + 0x000)
#define SYNCR   *(unsigned short int *) (MCBASE + 0x004)
#define PICR    *(unsigned short int *) (MCBASE + 0x022)
#define PITR    *(unsigned short int *) (MCBASE + 0x024)
#define CSAMR0  *(unsigned int *) (MCBASE + 0x040)
#define CSBAR0  *(unsigned int *) (MCBASE + 0x044)
#define CSAMR1  *(unsigned int *) (MCBASE + 0x048)
#define CSBAR1  *(unsigned int *) (MCBASE + 0x04C)
#define CSAMR2  *(unsigned int *) (MCBASE + 0x050)
#define CSBAR2  *(unsigned int *) (MCBASE + 0x054)
#define CSAMR3  *(unsigned int *) (MCBASE + 0x058)
#define CSBAR3  *(unsigned int *) (MCBASE + 0x05C)
/******DMA*****/
#define DMAMCR1 *(unsigned short int *) (MCBASE + 0x780)
#define INTR1   *(unsigned short int *) (MCBASE + 0x784)
#define CCR1    *(unsigned short int *) (MCBASE + 0x788)
#define CSR1    *(unsigned char *) (MCBASE + 0x78A)
#define FCR1    *(unsigned char *) (MCBASE + 0x78B)
#define SAR1    *(unsigned int *) (MCBASE + 0x78C)
#define DAR1    *(unsigned int *) (MCBASE + 0x790)
#define BTC1    *(unsigned int *) (MCBASE + 0x794)
#define DMAMCR2 *(unsigned short int *) (MCBASE + 0x7A0)
#define INTR2   *(unsigned short int *) (MCBASE + 0x7A4)
#define CCR2    *(unsigned short int *) (MCBASE + 0x7A8)
#define CSR2    *(unsigned char *) (MCBASE + 0x7AA)
#define FCR2    *(unsigned char *) (MCBASE + 0x7AB)
#define SAR2    *(unsigned int *) (MCBASE + 0x7AC)
#define DAR2    *(unsigned int *) (MCBASE + 0x7B0)
#define BTC2    *(unsigned int *) (MCBASE + 0x7B4)
/******Serial Modules*****/
#define SMCR   *(unsigned short int *) (MCBASE + 0x700)
#define ILR    *(unsigned char *) (MCBASE + 0x704)
#define IVR    *(unsigned char *) (MCBASE + 0x705)
#define MR1A   *(unsigned char *) (MCBASE + 0x710)
#define SRA    *(unsigned char *) (MCBASE + 0x711)
#define CSRA   *(unsigned char *) (MCBASE + 0x711)
#define CRA    *(unsigned char *) (MCBASE + 0x712)
#define RBA    *(unsigned char *) (MCBASE + 0x713)
#define TBA    *(unsigned char *) (MCBASE + 0x713)
```

```

#define MR2A      *(unsigned char *) (MCBASE + 0x720)
#define MR1B      *(unsigned char *) (MCBASE + 0x718)
#define SRB       *(unsigned char *) (MCBASE + 0x719)
#define CSRB      *(unsigned char *) (MCBASE + 0x719)
#define CRB       *(unsigned char *) (MCBASE + 0x71A)
#define RBB       *(unsigned char *) (MCBASE + 0x71B)
#define TBB       *(unsigned char *) (MCBASE + 0x71B)
#define MR2B      *(unsigned char *) (MCBASE + 0x721)
#define IPCR      *(unsigned char *) (MCBASE + 0x714)
#define ACR       *(unsigned char *) (MCBASE + 0x714)
#define ISR       *(unsigned char *) (MCBASE + 0x715)
#define IER       *(unsigned char *) (MCBASE + 0x715)
#define IP        *(unsigned char *) (MCBASE + 0x71D)
#define OPCR      *(unsigned char *) (MCBASE + 0x71D)
#define OPS       *(unsigned char *) (MCBASE + 0x71E)
#define OPR       *(unsigned char *) (MCBASE + 0x71F)
/*******************************************************/

/******Timer Modules******/
#define TMMCR1    *(unsigned short int *) (MCBASE + 0x600)
#define IR1       *(unsigned short int *) (MCBASE + 0x604)
#define CR1       *(unsigned short int *) (MCBASE + 0x606)
#define SR1       *(unsigned short int *) (MCBASE + 0x608)
#define CNTR1     *(unsigned short int *) (MCBASE + 0x60A)
#define PREL1T1   *(unsigned short int *) (MCBASE + 0x60C)
#define PREL2T1   *(unsigned short int *) (MCBASE + 0x60E)
#define COM1      *(unsigned short int *) (MCBASE + 0x610)
#define TMMCR2    *(unsigned short int *) (MCBASE + 0x640)
#define IR2       *(unsigned short int *) (MCBASE + 0x644)
#define CR2       *(unsigned short int *) (MCBASE + 0x646)
#define SR2       *(unsigned short int *) (MCBASE + 0x648)
#define CNTR2     *(unsigned short int *) (MCBASE + 0x64A)
#define PREL1T2   *(unsigned short int *) (MCBASE + 0x64C)
#define PREL2T2   *(unsigned short int *) (MCBASE + 0x64E)
#define COM2      *(unsigned short int *) (MCBASE + 0x650)
/*******************************************************/

#endif

```

MC340BUG.H

```
*****  
/* File Name : MC340BUG.H */  
/* File Type : Header File */  
/* Created On : 03/17/95 */  
/* Modified On: 06/05/95 */  
/* Created By : Faisal Habib */  
/* Description: This header file declares the fuctions that are */  
/* provided in the 340Bug Monitor. The functions use */  
/* 340Bug Trap #15 handler, which allow system calls from */  
/* user programs. */  
*****  
*****  
/* WARNING!! : IF YOU ARE NOT USING THE MOTOROLA 340BUG MONITOR THEN */  
/* DO NOT INCLUDE THIS HEADER FILE. PROGRAMS USING THIS */  
/* HEADER FILE WILL FUNCTION PROPERLY ONLY IF THE 340BUG */  
/* IS USED. */  
/*  
/* WARNING!! : DO NOT USE TRAP #15 FOR USER PROGRAMS. TRAP #15 IS */  
/* USED FOR SYSTEM CALLS. */  
*****  
  
#ifndef __MC340BUG_H  
#define __MC340BUG_H  
  
#define NULL ((void *)0)  
#define EOF (-1)  
  
extern void ERASLN();  
extern void NEWLN();  
extern char getchar();  
extern void putchar(char);  
extern void puts(char *);  
extern void PrintHex(unsigned short int);  
extern void RET340BUG();  
  
#endif
```

HARDWARE.H

```
/************************************************************************/
/* File Name : HARDWARE.H                                         */
/* File Type : C header file                                       */
/* Created On : 05/04/95                                         */
/* Modified On: 05/23/95                                         */
/* Created By : Faisal Habib                                       */
/* Description: This header file contains macros and function prototypes */
/*               for the source program. The source program will test the */
/*               hardware interface for the TNT and MC68340. In particular*/
/*               it will test the three different types of I/O: Programmed, */
/*               Interrupts, and DMA.                                     */
/************************************************************************

#ifndef __HARDWARE_H
#define __HARDWARE_H

#define WRITE 0
#define READ 1
#define IARB 0x0008
#define IRQ3 0x08

#define AVECIRQ3 0x0000006C

#define EnableMC68340Interrupts asm("ori.w #$0200,SR", "andi.w #$FAFF,SR" )

#define DMA_READ 0x1AA2
#define DMA_WRITE 0x06A2
#define DMA_CONF 0x177A
#define DMA_INTR 0x000F
#define DMA_SPACE 0xDD

#define DMA_DONE 0x40
#define DMA_BES 0x20
#define DMA_BED 0x10
#define DMA_CON 0x08
#define StartDMA CCR1 |= 0x01

void ConfigureMC();
char Programmed_IO_Test();
char Interrupt_IO_Test();
char DMA_IO_Test();
char SetupDMA(unsigned char,unsigned int,unsigned short int*);
unsigned short int Check_DMA_Status(unsigned char);
char Compare(unsigned short int*,unsigned short int*);
char Select();

#endif
```

HARDWARE.C

```
*****
/* File Name : HARDWARE.C */
/* File Type : C source file */
/* Created On : 05/04/95 */
/* Modified On: 05/24/95 */
/* Created By : Faisal Habib */
/* Description: This program will test the hardware interface for the */
/* TNT and MC68340. In particular it will test the three */
/* different types of I/O: Programmed, Interrupts, and DMA. */
*****
```

```
*****
/* WARNING : DO NOT USE THIS PROGRAM IF YOU USE AN INTERRUPT LEVEL OTHER */
/* THAN IRQ3 OF THE MC68340 AND A BASE ADDRESS OTHER THAN */
/* $FFF800. YOU CAN CHANGE THE BASE ADDRESS AND INTERRUPT */
/* LEVEL IN THE HEADER FILE AND RE-COMPILe THE SOURCE CODE. */
*/
/* WARNING : THIS PROGRAM USES THE MC340BUG LIBRARY. THEREFORE TRAP #15 */
/* IS NOT AVAILABLE FOR USER PROGRAMS. PLEASE REFRAIN FROM */
/* USING TRAP #15 CALLS. */
*****
```

```
#include "REGISTER.H"                                /*TNT Register Definitions*/
#include "MC340BUG.H"                                /*340bug routines*/
#include "MC68340.H"                                /*MC68340 register def. */
#include "TEST4882.H"                                /*TNT config. functions */
#include "HARDWARE.H"                                /*Hardware test header */
*****
```

```
/* The main routine conducts three different types of tests and prints */
/* the final results. The three tests are: */
/*
*           1. Programmed I/O
*           2. Interrupt Driven I/O
*           3. DMA I/O
*/
/* To run the above tests, MC68340 and TNT4882 need to be configured. */
*****
```

```
*****
```

```
main()
{
    char fail;                                     /*var. for storing results*/
    unsigned int counter;

    fail = FALSE;

    ConfigureMC();                                /*configure MC68340 */
    puts("\nMC68340 has been initialized.\n");
    InitializeTNT();                             /*initialize the TNT4882 */
    puts("\nTNT4882 has been initialized.\n\n");
    while (1)
    {
        switch (Select())
        {
            case 0:                                /*Test Interface once */
                fail |= Programmed_IO_Test();
                fail |= Interrupt_IO_Test();
                /*fail |= DMA_IO_Test();*/
                break;

            case 1:                                /*Loop Test (500 times) */
                for (counter=0;counter<500;++counter)
```

```

    {
        NEWLN();
        PrintHex(counter);
        puts("Loop");
        fail |= Programmed_IO_Test();
        fail |= Interrupt_IO_Test();
        /*fail |= DMA_IO_Test();*/
    }
    break;

    default:
        NEWLN();
        RET340BUG();
    }

    if (fail)
        puts("\nHardware Diagnostics Completed. Board is not fully functional.\n");
    else
        puts("\nHardware Diagnostics Completed. Board is fully functional.\n");
}
}
//****************************************************************************
//****************************************************************************
/*  Module      : ConfigureMC()                                     */
/*  Parameters   : NONE                                         */
/*  Return Type  : void                                         */
/*  Created On   : 05/04/95                                       */
/*  Modified On  : 05/15/95                                       */
/*  Description  : Configures the MC68340 CPU.                   */
/*                 Loads the interrupt handler for IRQ3           */
/*                 Configures the SIM for unrestricted data space,no show */
/*                           cycles, partial interrupt request mode. */
/* */
/*                 To place the TNT in a different address space, assign */
/*                           appropriate values to the chip select registers. */
/*                 To change the interrupt priority, make changes to the */
/*                           HARDWARE.H file. */
/* */
/*  Reference   : MC68340 User's Manual (MC68340UM/AD Rev 1) Section 4. */
//****************************************************************************

//****************************************************************************
void ConfigureMC()
{
    unsigned int *Exception;
    (unsigned int)Exception = AVECIRQ3;
    CSBAR2 = 0x00FFEFF1;                                /*CS base address register*/
    CSAMR2 = 0x0000007F3;                                /*CS address mask register*/

    SIMMCR = IARB;                                     /*configure SIM           */
    AVR = IRQ3;                                       /*autovector for IRQ3   */
    *Exception = (unsigned int)handler;                  /*load interrupt handler*/
}
//****************************************************************************

//****************************************************************************
/*  Module      : Programmed_IO_Test()                           */
/*  Parameters   : NONE                                         */
/*  Return Type  : char                                         */
/*  Created On   : 05/04/95                                       */
/*  Modified On  : 05/15/95                                       */
/*  Description  : Performs 5 types of Programmed I/O tests: */
/* */

```

```

/*
   1. 8 Bit accesses to FIFO A
   2. 8 Bit accesses to FIFO B
   3. 16 Bit accesses to FIFOs
   4. 8 Bit WRITES and 16 Bit READS
   5. 16 Bit WRITES and 8 Bit READS
*/
/* Reference : MC68340 & TNT4882 Application Notes */
//********************************************************************

//********************************************************************

char Programmed_IO_Test()
{
    char result = FALSE;
    HSSEL |= E_NODMA;

    puts("\nPerforming Programmed I/O Test.\n");

    CMDR = RstFIFO;
    puts("  Performing 8 Bit accesses to FIFO A");
    result |= Test8BitRegister(&FIFOA);
    CMDR = RstFIFO;
    puts("  Performing 8 Bit accesses to FIFO B");
    result |= Test8BitRegister(&FIFOB);

    CMDR = RstFIFO;
    puts("  Performing 16 Bit accesses to FIFOs");
    result |= Test16BitRegister();

    CMDR = RstFIFO;
    puts("  Performing 8 Bit WRITES & 16 Bit READS");
    result |= Test8Write16Read();

    CMDR = RstFIFO;
    puts("  Performing 16 Bit WRITES & 8 BIT READS");
    result |= Test16Write8Read();

    return result;
}
//********************************************************************

//********************************************************************

/* Module      : Interrupt_IO_Test() */
/* Parameters  : NONE */
/* Return Type : char */
/* Created On  : 05/04/95 */
/* Modified On : 05/15/95 */
/* Description : Performs Interrupt Driven I/O tests */
/*                 Checks the installation of the interrupt handler */
/* Reference   : MC68340 & TNT4882 Application Notes */
//********************************************************************

//********************************************************************

char Interrupt_IO_Test()
{
    unsigned int *Exception;
    (unsigned int)Exception = AVECIRQ3;

    puts("\nPerforming Interrupt I/O Test.\n");
    puts("  Checking Interrupt Handler Installation");
    if ((unsigned int)handler != *Exception)
    {
        puts("Interrupt Handler is not loaded properly. Interrupt Tests will not be per-

```

```

formed.\n\n");
    return ERROR;
}
else
{
    Failure = FALSE;
    EnableMC68340Interrupts;
    IMR3 = E_NFF;                                /*write to fifo      */
    while (IMR3 & E_NFF);
    EnableMC68340Interrupts;
    IMR3 = E_NEF;                                /*read from fifo      */
    while (IMR3 & E_NEF);
}
return Failure;
}
/*****************************************/
/*****************************************/
/*  Module      : DMA_IO_Test()          */
/*  Parameters   : NONE                */
/*  Return Type  : char                */
/*  Created On   : 05/04/95            */
/*  Modified On  : 05/17/95            */
/*  Description  : Performs DMA I/O tests */
/*  Reference   : MC68340 & TNT4882 Application Notes */
/*****************************************/
/*****************************************/
char DMA_IO_Test()
{
    unsigned short int StoreBuf[] =
{'a','b','c','d','e','f','g','h','i','j','k','l','m','n','o','p'};
    unsigned short int ReceiveBuf[16];
    puts("\nPerforming DMA I/O Test.\n");
    HSSEL = E_ONEC;                                /*one-chip mode      */
    CMDR = RstFIFO;                                /*reset the FIFOs    */
    CFG = 0x11;                                    /*GPIB Write          */
    puts("  Performing WRITE to FIFOs using DMA");
    if (SetupDMA(READ,16,StoreBuf) == ERROR) return ERROR;
    StartDMA;
    while (BTC1);

    CFG = 0x01;                                    /*GPIB Read          */
    puts("  Performing READ from FIFOs using DMA");
    if (SetupDMA(WRITE,16,ReceiveBuf) == ERROR) return ERROR;
    StartDMA;
    while (BTC1);

    return Compare(StoreBuf,ReceiveBuf);
}
/*****************************************/
/*****************************************/
/*  Module      : SetupDMA()           */
/*  Parameters   : unsigned char,unsigned int,unsigned short int* */
/*  Return Type  : char                */
/*  Created On   : 05/15/95            */
/*  Modified On  : 05/17/95            */
/*  Description  : Sets and configures the DMA channels for READ or WRITE */
/*                 For a different configuration, change the values in the */
/*                 HARDWARE.H file.                                         */
/*  Reference   : MC68340 & TNT4882 Application Notes */
/*****************************************/

```

```

/********************************************/
/* **** **** **** **** **** **** **** **** */
char SetupDMA(unsigned char ioType,unsigned int count,unsigned short int *buffer)
{
    DMAMCR1 = DMA_CONF;
    INTR1 = DMA_INTR;
    CCR1 = 0;
    CSR1 = 0x7C;                                /*clear status register */
    FCR1 = DMA_SPACE;                            /*set for DMA space */
    BTC1 = count;                                /*set the number of bytes */
    switch (ioType)
    {
        case READ:                            /*READ from Memory */
            CCR1 = DMA_READ;
            SAR1 = (unsigned int)buffer;
            break;
        case WRITE:                            /*WRITE to Memory */
            CCR1 = DMA_WRITE;
            DAR1 = (unsigned int)buffer;
            break;
        default:                                /*This should never happen*/
            puts("ERROR!! Incorrect I/O type for DMA");
            return ERROR;
    }
    return FALSE;
}
/********************************************/
/* **** **** **** **** **** **** **** **** */

/* Module      : Compare() */
/* Parameters  : unsigned short int*,unsigned short int* */
/* Return Type : char */
/* Created On  : 05/04/95 */
/* Modified On : 05/15/95 */
/* Description : Compares the two arrays and displays an error message */
/*               if mismatch occurs */
/* Reference   : MC68340 & TNT4882 Application Notes */
/* **** **** **** **** **** **** **** **** */

/********************************************/
/* **** **** **** **** **** **** **** **** */
char Compare(unsigned short int *s,unsigned short int *r)
{
    char result;
    int i;

    result = FALSE;

    for (i=0;i<16;++i)
        if(s[i] != r[i])                      /*if different then show */
        {                                     /* error message. */
            DisplayErrorMessage(r[i],s[i]);
            result = ERROR;
        }
    return result;
}
/********************************************/
/* **** **** **** **** **** **** **** **** */

/* Module      : Select() */
/* Parameters  : NONE */
/* Return Type : char */
/* **** **** **** **** **** **** **** **** */

```

```
/* Created On  : 05/23/95 */  
/* Modified On : 05/23/95 */  
/* Description : This routine prints a selection screen so that the user */  
/*                can select a particular test. */  
/* Reference   : MC68340 & TNT4882 Application Notes */  
//*********************************************************************/*  
*****  
char Select()  
{  
    puts("      1.  Test Interface");  
    puts("      2.  Loop Test");  
    puts("      3.  Exit");  
    puts("\nOPTION====> ");  
    return (getchar() - 0x31);  
}  
*****
```

TEST4882.H

```
*****  
/* File Name : TEST4882.H */  
/* File Type : C header file */  
/* Created On : 05/04/95 */  
/* Modified On: 05/23/95 */  
/* Created By : Faisal Habib */  
/* Description: This header file contains function prototypes for the C */  
/* source program. */  
*****  
  
#ifndef __TEST4882_H  
#define __TEST4882_H  
  
#define TRUE 1  
#define FALSE 0  
#define ERROR 1  
  
char Failure;  
  
extern void InitializeTNT();  
extern void interrupt handler();  
extern char Test8BitRegister(unsigned char*);  
extern char Test16BitRegister();  
extern char Test8Write16Read();  
extern char Test16Write8Read();  
extern char InterruptWriteTest();  
extern char InterruptReadTest();  
extern void DisplayErrorMessage(unsigned short int,unsigned short int);  
extern char AskUser();  
  
#endif
```

TEST4882.C

```
*****
/* File Name : TEST4882.C */
/* File Type : C source file */
/* Created On : 05/04/95 */
/* Modified On: 05/24/95 */
/* Created By : Faisal Habib */
/* Description: This file contains routines that are used by the hardware */
/* test program to test the MC68340 & TNT4882 Interface. */
*****
```

```
*****
/* WARNING : THIS PROGRAM USES THE MC340BUG LIBRARY. THEREFORE TRAP #15 */
/* IS NOT AVAILABLE FOR USER PROGRAMS. PLEASE REFRAIN FROM */
/* USING TRAP #15 CALLS. */
*****
```

```
#include "REGISTER.H"           /*TNT Register Definitions */
#include "MC340BUG.H"           /*340 BUG Monitor routines */
#include "TEST4882.H"           /*Header file for TEST4882.C */
*****
```

```
*****
/* Global arrays containing test patterns for 16 bit tests. These arrays*/
/* are used in the following routines: */
/* */
/*      Test16BitRegister() */
/*      Test8Write16Read() */
/*      Test16Write8Read() */
*****
```

```
unsigned char TestBit8[14] =
{0x00,0xFF,0xAA,0xCC,0xF0,0xFF,0x00,0xFF,0xAA,0xCC,0xF0,0x00};
unsigned short int TestBit16[7] = {0x0000,0xFFFF,0xAAAA,0xCCCC,0xF0F0,0xFF00,0x0000};
```

```
*****
/* Module      : handler() */
/* Parameters  : NONE */
/* Return Type : void */
/* Created On  : 05/04/95 */
/* Modified On : 05/10/95 */
/* Description : Handler for GPIB I/O. This routine is entered when the */
/*               TNT chip asserts its interrupt signal. The interrupts */
/*               should be enabled for interrupts to occur. */
/* */
/*      The handler handles two cases of interrupts. These cases */
/*      are INPUT, and OUTPUT. The handler can be easily */
/*      expanded by providing other cases in the IF-ELSE. */
*****
```

```
*****
interrupt void handler()
{
    if (ISR3 & IMR3 & E_NFF)           /*FIFO is not full */
    {
        IMR3 &= ~E_NFF;               /*clear the source of interrupt */
        Failure |= InterruptWriteTest(); /*perform the write test */
    }
    else if (ISR3 & IMR3 & E_NEF)      /*FIFO is empty */
    {
        IMR3 &= ~E_NEF;               /*clear the source of interrupt */
        Failure |= InterruptReadTest(); /*perform the read test */
    }
    else puts("ERROR !! False Interrupt Occurred.");
}
```

```

}

//****************************************************************************

/*
*  Module      : InitializeTNT()
*  Parameters   : NONE
*  Return Type : void
*  Created On  : 05/04/95
*  Modified On : 05/24/95
*  Description  : This is the Initialization routine. This routine should
*                 be called during the start up sequence.
*
*                 InitializeTNT places the TNT in one chip mode.
*
*  Reference   : ESP-488TL Software Reference Manual for TNT4882
*/
//************************************************************************

void InitializeTNT()
{
    CMDR = SftRst;                      /*perform soft reset          */
    SPMR = E_S8;                        /*place the TNT in turbo mode */
    AUXMR = AUXRA;
    AUXMR = (E_BIN|E_XEOS|E_HLDA);
    KEYREG = 0;
    HSSEL = E_ONEC;                    /*place TNT in one chip mode */
    AUXMR = RstChip;                  /*issue a chip reset          */
    AUXMR = HLDI;                      /*holdoff immediately command */
    AUXMR = PON;                      /*issue power on              */
}
//************************************************************************

/*
*  Module      : Test8BitRegister()
*  Parameters   : unsigned char*
*  Return Type : char
*  Created On  : 05/04/95
*  Modified On : 05/04/95
*  Description  : This routine tests the 8 bit registers. It writes all
*                 possible values (0-255). By doing so it tests the
*                 functionality of the TNT data bus.
*/
//************************************************************************

char Test8BitRegister(unsigned char *Register)
{
    unsigned char StoredValue,Loop,NumOfBytes,result;
    result = FALSE;
    for (Loop=0;Loop<255;Loop+=15)        /*writing all possible values... */
    {                                     /*...15 at a time               */
        for (NumOfBytes=0;NumOfBytes<=15;++NumOfBytes)
            *Register = Loop + NumOfBytes;
        for (NumOfBytes=0;NumOfBytes<=15;++NumOfBytes)
        {
            StoredValue = *Register;      /*read values from the 8 bit regs.*/
            if (StoredValue != (Loop+NumOfBytes))
            {                           /*if values differ, generate error*/
                DisplayErrorMessage(StoredValue,(Loop+NumOfBytes));
                if (!(AskUser())) return ERROR; /*ask user to continue testing? */
                result = ERROR;
            }
        }
    }
}

```

```

        }
        return result;
    }
//********************************************************************

//********************************************************************/
/*  Module      : Test16BitRegister()                               */
/*  Parameters   : NONE                                         */
/*  Return Type  : char                                         */
/*  Created On   : 05/04/95                                     */
/*  Modified On  : 05/24/95                                     */
/*  Description  : This routine tests 16 bit accesses to the fifos. It */
/*                 writes then reads the pattern stored in TestBit16[].   */
//********************************************************************

//********************************************************************/
char Test16BitRegister()
{
    unsigned char result;
    unsigned short int StoredValue,Loop;
    result = FALSE;
    for (Loop=0;Loop<6;++Loop)
        FIFO = TestBit16[Loop];
    for (Loop=0;Loop<6;++Loop)
    {
        StoredValue = FIFO;
        if (StoredValue != TestBit16[Loop])
        {
            DisplayErrorMessage(StoredValue,TestBit16[Loop]);
            if(!AskUser()) return ERROR;
            result = ERROR;
        }
    }
    return result;
}
//********************************************************************

//********************************************************************/
/*  Module      : Test8Write16Read()                             */
/*  Parameters   : NONE                                         */
/*  Return Type  : char                                         */
/*  Created On   : 05/04/95                                     */
/*  Modified On  : 05/23/95                                     */
/*  Description  : This routine does 8 bit writes and 16 bit reads from the */
/*                 fifos. This test makes sure that fifos are accessed */
/*                 properly.                                         */
//********************************************************************

//********************************************************************/
char Test8Write16Read()
{
    unsigned short int StoredValue;
    unsigned short int Loop,result;
    result = FALSE;
    for (Loop=0;Loop<6;++Loop)
    {
        FIFOA = TestBit8[Loop];           /*8 bit writes from TestBit8[] */
        FIFOB = TestBit8[Loop+6];
    }
    for (Loop=0;Loop<6;++Loop)
    {
        StoredValue = FIFO;           /*16 bit read from FIFO */
    }
}

```

```

        if (StoredValue != TestBit16[Loop]) /*compare w/ values in TestBit16[]*/
        {
            DisplayErrorMessage(StoredValue,TestBit16[Loop]);
            if (!(AskUser())) return ERROR;
            result = ERROR;
        }
    }
    return result;
}
//********************************************************************

/*
 *  Module      : Test16Write8Read()
 *  Parameters  : NONE
 *  Return Type : char
 *  Created On  : 05/04/95
 *  Modified On : 05/23/95
 *  Description : This routine does 16 bit writes and 8 bit reads from the
 *                 fifos.  This test makes sure that fifos are accessed
 *                 properly.
 */
//********************************************************************

char Test16Write8Read()
{
    unsigned char ValueA,ValueB,result,Loop;
    result = FALSE;
    for (Loop=0;Loop<6;++Loop)
        FIFO = TestBit16[Loop];           /*16 bit writes from TestBit16[] */
    for (Loop=0;Loop<6;++Loop)
    {
        ValueA = FIFOA;               /*8 bit read from FIFO A */
        ValueB = FIFOB;               /*8 bit read from FIFO B */

        if (ValueA != TestBit8[Loop])    /*compare w/ values in TestBit8[] */
        {
            puts("FIFO A Error");
            DisplayErrorMessage(ValueA,TestBit8[Loop]);
            if (!(AskUser())) return ERROR;
            result = ERROR;
        }

        if (ValueB != TestBit8[Loop+6])   /*compare w/ values in TestBit8[] */
        {
            puts("FIFO B Error");
            DisplayErrorMessage(ValueB,TestBit8[Loop+7]);
            if (!(AskUser())) return ERROR;
            result = ERROR;
        }
    }
    return result;
}
//********************************************************************

/*
 *  Module      : InterruptWriteTest()
 *  Parameters  : NONE
 *  Return Type : char
 *  Created On  : 05/04/95
 *  Modified On : 05/04/95
 *  Description : This routine is entered during an interrupt if WRITE is
 *                 to be performed.  This routine simply writes values to
 */

```

```

/*
   the fifos. The values are read during a READ interrupt.*/
//********************************************************************

//********************************************************************/
char InterruptWriteTest()
{
    unsigned short int counter;
    CMDR = RstFIFO;
    puts("  Performing WRITE to FIFOs using interrupts");
    for (counter = 0;counter<15;++counter)
        FIFO = counter;
    return FALSE;
}
//********************************************************************/
/*  Module      : InterruptReadTest()                               */
/*  Parameters   : NONE                                         */
/*  Return Type  : char                                         */
/*  Created On   : 05/04/95                                     */
/*  Modified On  : 05/04/95                                     */
/*  Description  : This routine reads the values written by the interrupt */
/*                 write routine. Error messages are displayed if a      */
/*                 mismatch occurs.                                     */
//********************************************************************

//********************************************************************/
char InterruptReadTest()
{
    unsigned char result;
    unsigned short int counter,StoredValue;

    result = FALSE;
    puts("  Performing READ to FIFOs using interrupts");
    for (counter = 0;counter<15;++counter)
    {
        StoredValue = FIFO;
        if (StoredValue != counter)
        {
            DisplayErrorMessage(StoredValue,counter);
            if (!(AskUser())) return ERROR;
            result = ERROR;
        }
    }
    return result;
}
//********************************************************************

//********************************************************************/
/*  Module      : DisplayErrorMessage()                            */
/*  Parameters   : unsigned short int,unsigned short int        */
/*  Return Type  : void                                         */
/*  Created On   : 05/04/95                                     */
/*  Modified On  : 05/04/95                                     */
/*  Description  : Displays error message along with right & wrong values */
//********************************************************************

//********************************************************************/
void DisplayErrorMessage(unsigned short int WrongValue,unsigned short int RightValue)
{
    puts("\nAn Error Occurred.");
    PrintHex(RightValue);
    puts(":  Expected Value");
    PrintHex(WrongValue);
}

```

```

    puts(": Received Value");
}
//********************************************************************

//********************************************************************/
/*  Module      : AskUser()
/*  Parameters  : NONE
/*  Return Type : char
/*  Created On  : 05/04/95
/*  Modified On : 05/04/95
/*  Description : This routine prompts the user for the continuation of
/*                 of a test.
//********************************************************************

//********************************************************************/
char AskUser()
{
    char choice;
    puts("Do you wish to continue (Y/N):\n");
    while (choice = getchar())           /*read characters until y,Y,n,N */
    {
        if ((choice == 'y') || (choice == 'Y')) return TRUE;
        if ((choice == 'n') || (choice == 'N')) return FALSE;
    }
}
//********************************************************************/

```



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